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Claims

- 1. A method for computing a Wave Transfer Vector based on the reciprocity principle, comprising the steps of:
- simulating positioning of a monopole, omnidirectional wave energy source at a reference position remote from a body; computing a boundary oscillation amplitude of the wave generated by the source at a surface of the body; and deriving from the boundary oscillation amplitude said Wave Transfer Vector.
- 10 2. The method of claim 1 wherein the computing step is carried out by a numerical method.
 - 3. The method according to claim 2 wherein the numerical method is one of: a finite element method, a combination of the finite and infinite element methods, a direct boundary element method, a direct multi-domain boundary element method, an indirect boundary element method
 - 4. The method according to claim 1, wherein wave source is an acoustic source.
 - 5. The method according to claim 1 further comprising a step of computing an additional Wave Transfer Vector comprising:
- 20 computing at least a first and a second wave transfer vector at a first and a second predetermined frequency, respectively, and computing the additional Wave Transfer Vector at a frequency intermediate the first and second frequency by interpolation between the first and second Wave Transfer Vectors.
- 25 6. The method of claim 5 wherein the interpolation technique is one of a polynomial interpolation mechanism and a spline interpolation mechanism.
 - 7. The method according to claim 1 wherein the Wave Transfer Vector is an Acoustic Transfer Vector, further comprising the step of computing a Modal Acoustic Transfer Vector (MATV) from an acoustic transfer vector (ATV) in an alternative coordinate system defined by a set of deformed shapes of a body.
- alternative coordinate system defined by a set of deformed shapes of a body, comprising:
 - projecting the ATV into the alternative coordinate system.

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- 8. The method of claim 7 further comprising the step of: using the MATV to predict a response of the body or the effect of such a response at a reference point remote from the body.
- 9. A processing engine adapted to carry out any of the methods of claim 1 to 8.
 - 10. A computer program product for executing on a computer, the computer program product executing any of the method steps of claim 1 to 8 when executed on the computer.
- 11. A method of inputting at a near terminal a representation of a body and coordinates of a reference point and transmitting these to a remote terminal running a program for executing any of the methods of claim 1 to 8, and receiving at a near location an output of any of the methods.
- 12. The method according to claim 11, wherein the output is one of: an ATV, an oscillation amplitude such as an acoustic pressure level, a surface vibration of the body, a revised design of at least a part of the body.
 - 13. A computer system for computing a Wave Transfer Vector based on the reciprocity principle, comprising: means for simulating positioning of a monopole, omnidirectional wave energy source at a reference position remote from a body;
- 20 means for computing a boundary oscillation amplitude of the wave generated by the source at a surface of the body; and means for deriving from the boundary oscillation amplitude said Wave Transfer Vector.
- 14. The computer system according to claim 13, further comprising means for computing an additional Wave Transfer Vector at a frequency intermediate a first and second frequency by interpolation between a first and a second Wave Transfer Vector at th first and second frequencies.
 - 15. The computer system according to claim 13 or 14, wherein the Wave Transfer Vector is an Acoustic Transfer Vector, further comprising: means for computing a Modal Acoustic Transfer Vector (MATV) from an acoustic transfer vector (ATV) in an alternative coordinate system defined by a set of deformed

shapes a body by projecting the ATV into the modal space.